



Smart Positioner - Non-contact Type





# SMARTPoz™ 8400SHN

The Forbes Marshall SMARTPoz™ 8400SHN smart positioner brings advanced sensor technology with numerous salient features. A simple to use, operator friendly device which is easy to adapt to control valve applications. Numerous functions can be easily achieved by simple configuration. The design lends itself for use in all process plants such as power, pharma, chemical, paper etc. It is built in an elegant aluminium pressure die cast case with environmental protection and yet easy to maintain.

#### Operating principle

SMARTPoz<sup>™</sup> 8400SHN is a two-wire device that uses a 4-20mA signal input as its set point, from which it derives its power. It compares the set point with the actual position of the actuator stem and eliminates the positioning error accurately using an internal PID control action.

This smart positioner has variants designed for use in both – safe and hazardous environments respectively. It is a microprocessor based positioner that provides fast, sensitive and accurate positioning for single acting linear pneumatic actuators.

SMARTPoz™ 8400SHN uses a unique contact-less magnetic position sensing technique in combination with a pair of Hall sensors. This mechanism is free from backlash and friction and helps achieve a fast and accurate position. The position sensing is contact-less and achieved by a combination of a shaft-mounted magnet and Hall-effect sensors mounted within the control unit.

The heart of the Positioner is a small piezo based transducer, which is a low power and low air consumption device. The electrical signal from the microcontroller is converted to precise equivalent pneumatic signals through the transducer, which operates the pilot valve, which in turn supplies proportional air to the valve actuator.

### **Block diagram** Exhaust HALL Sensor 1 Inlet air Internal pressure AFR MAGNET MOVEMENT . 3-6 bar /D DISPLAY Piezo valve Pilot CPU valve ď Controlled output to actuator HALL Position Output\* Sensor 2 Control Terminal blocks FMPoz HALL sensor \*Option dependent 0-0-0 Cable glands 8400SHN

| Operating specifications |   |  |  |  |  |
|--------------------------|---|--|--|--|--|
| Position sensing         | HALL sensor : magnetic link-free sensing  |  |  |  |  |
| Controller type          | Microprocessor based non-contact type   |  |  |  |  |
| Stroke length            | 16, 20, 30, 60, 100 mm  |  |  |  |  |
| Valve characteristics    | Linear, Equal %, Inv Equal%, free adjustment  |  |  |  |  |
| Actuator type            | Single-acting, linear pneumatic actuator. • MF series • U series  |  |  |  |  |
| Control input (SP)       | 4-20mA  |  |  |  |  |
| Display                  | Custom alphanumeric LCD with bar graph  |  |  |  |  |
| User input               | Via Tactile keys : require opening of Lid HALL-effect switches: externally operable using bar magnet  |  |  |  |  |
| Operating power          | 4-20mA control input signal, with Compliance voltage 10VDC to maintain current of ≥3.4mA at 500 Ohms. It is mandatory to maintain Compliance voltage 10VDC minimum to keep the positioner ON. |  |  |  |  |
| Operating temperature    | [-] 20 °C to [+] 80 °C  |  |  |  |  |
| Pneumatic input          | 1.5 – 6 bar pressure  |  |  |  |  |
| Air Quality              | Filtered with 5 microns, Oil Class : 3 (< 1 ppm), Dried according to ISO8573-1 Class 3 Humidity – Class I   |  |  |  |  |
| Air consumption          | < 0.02 m³/hr at 6 Bar air pressure  |  |  |  |  |

| Position transmitter (optional) |  |  |  |  |
|---------------------------------|--|--|--|--|
| Position feedback signal        | Passive 4-20mA output                    |  |  |  |
| External power supply           | Vs = 12 to 30 VDC max. RI = [Vs-5V]/20mA |  |  |  |
| Temperature stability           | 0.2% /10° K of full scale                |  |  |  |
| Accuracy of position feedback   | ± 0.5% of Span                           |  |  |  |
| Communication                   | 4-20 mA                                  |  |  |  |

|                                   | Standard  | Specially for Ex-Proof / Intrinsically Safe                            |  |  |  |  |  |  |
|-----------------------------------|---|--|--|--|--|--|--|--|
| Connections                       |   |  |  |  |  |  |  |  |
| Terminations                      | Screw type, for 1sqmm conductor termination                       | Additional stud for EARTH connection                                   |  |  |  |  |  |  |
| Cable gland                       | M20 x 1.5mm single compression                                    | M20 x 1.5mm Double compression   |  |  |  |  |  |  |
| Cable construction                | 2 core, 1sqmm each conductor, 7-12mm OD                           | 2 core, 1sqmm each conductor, 7-12mm OD                                |  |  |  |  |  |  |
| Cable specs                       | Cable inductance : 3.05mH max                                     | Cable inductance : 3.05mH max  |  |  |  |  |  |  |
|                                   | Cable capacitance : 0.083 µF max                                  | Cable capacitance : 0.083 µF max                                       |  |  |  |  |  |  |
| Cable type                        | Control input : Unshielded 2 core<br>Feedback : Unshielded 2 core | Control input : Armored 3 core (input+EARTH) Feedback : Armored 2 core |  |  |  |  |  |  |
| Pneumatic connection              | 1/4" NPT(F)   |  |  |  |  |  |  |  |
| Enclosure                         |   |  |  |  |  |  |  |  |
| Housing                           | Aluminium pressure die cast (same for safe & hazardous area)      |  |  |  |  |  |  |  |
| Weight                            | 3 kgs   |  |  |  |  |  |  |  |
| Area Classification and Approvals |   |  |  |  |  |  |  |  |
| Ingress protection                | IP 66   |  |  |  |  |  |  |  |
| Certification EMC, EMI            | Conforms to IEC 61000-2, IEC 61000-4                              |  |  |  |  |  |  |  |
| Certification Ex                  | ATEX/ICEx, CE Marking   | Ex IIG Ex d IIC T6 Ex ia IIC   |  |  |  |  |  |  |
| Tests                             | Vibration Test : IEC 60068-2-6, Bump Test : IEC 60068-2-29        |  |  |  |  |  |  |  |

| Model de-codification     |        |      |               |         |                      |                 |                           |               |  |  |
|---------------------------|--------|------|---------------|---------|----------------------|-----------------|---------------------------|---------------|--|--|
| Model                     | Sensor |      | Communication |         | Position Transmitter |                 | Enclosure                 |               |  |  |
| 94000                     | ш      | HALL | NI            | 4-20 mA | N                    | Without POS. Tx | W                         | Weather proof |  |  |
| 8400S                     | П      | HALL | IN            | 4-20 MA | Т                    | With POS. Tx    | Е                         | Ex-proof*     |  |  |
| Ordering code : 8 4 0 0 S |        |      |               |         | * Intrinsic          | cally safe ve   | rsion available on reques |               |  |  |

**Example:** Model 8400SHNTW: Smart Positioner with Hall, Position transmitter and Weather Proof

#### **Salient Features**

Precise position control

Robust design.

Auto/manual calibration for full stroke

Low air consumption, which ensures payback of investment within few months

Can be used for linear, equal % characteristics irrespective of the Plug characteristics

Split range feature for two valves

Alphanumeric LCD display

Can be used for air to open, air to close application irrespective of actuator type

Magnetic feedback option

Basic programming front fascia without configurator

Retro-fitting of existing positioner is possible

NAMUR tubeless connection for MF-series actuators. Requires less space as external pneumatic tubing is not required

## Advantages of HALL based positioner

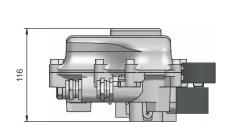
Contactless position feedback system

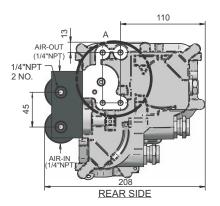
Free from backlash

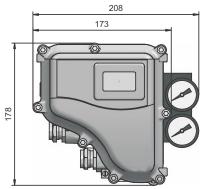
No wear and tear of hallfeedback parts because of contactless relative movement

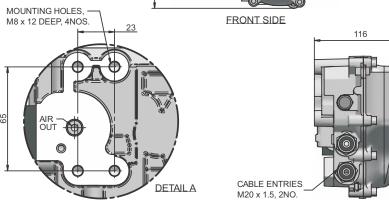
Easy maintenance

#### **Dimensions**











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